EMPATH Bearing Detection Case Study





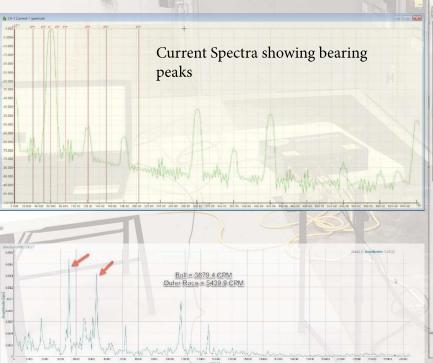
Bearing and winding failures due to harmonic and ground conditions in the motor and circuit.

300 horsepower, 1765 RPM, 6318ZZ bearings 40 Rotor Bars, 48 Stator Slots

Bearing Multipliers:

IR - 4.91/hz; OR - 3.09/hz; Cage - 0.39/hz; Ball - 2.09/hz

Actual RPM of motor during test = 1760.5 RPM



A Induction Motor [LF: 60 Hz] Results Time Freq. Bearings Phasors Extras Power factor Current Voltage Load VIt-GND ref.NOT neutral Connection Botor Stator (mechanical) Air gap Harmonic distortion Misalignment/Linhalance Bearing/Unidentified Bottom line **EMPATH Auto-Fault Detection** *Note: Noise floor is -80 db

Data collected from the MCC in a 48 second collection. As soon as the data was collected, the findings show in the EMPATH Auto-Fault Detection. Vibration was used to confirm the bearing conditions before removing the motor for repair. Stage 2 bearing fault detected



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